

Q1 (a) This is a separable DE.

$$\frac{dy}{dt} = -\frac{t}{y} \Rightarrow \int y dy = \int -t dt$$

$$\Rightarrow \frac{y^2}{2} + c_1 = -\frac{t^2}{2} + c_2$$

$$\Rightarrow y^2 = -t^2 + k$$

$$k = 2(c_2 - c_1)$$

$$\Rightarrow y(t) = \pm \sqrt{k - t^2}$$

(b)  $y(1) = -2 \Rightarrow$  we use the negative square root in the expression for  $y(t)$ .

$$\text{Then } -2 = -\sqrt{k - 1^2}$$

$$\Rightarrow (-2)^2 = (-\sqrt{k - 1})^2$$

$$\Rightarrow 4 = k - 1$$

$$\Rightarrow k = 5$$

so  $y(t) = -\sqrt{5 - t^2}$  is the solution to the IVP.

(c) This solution is defined if  $5 - t^2 \geq 0$

$$\text{i.e. } -\sqrt{5} \leq t \leq \sqrt{5}$$

[NB however that at  $t = \pm\sqrt{5}$ ,  $y = 0$  and so the DE is not properly defined.]

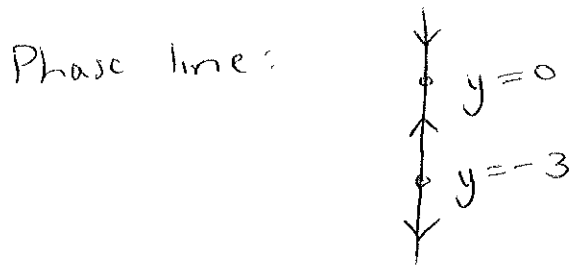
Q2 (a)  $\frac{dy}{dt} = -3y - y^2 = -y(3+y)$

Equilibria are  $y=0$  and  $y=-3$ .

$\frac{\partial f}{\partial y} = -3 - 2y$  ( $f(y) = -3y - y^2$ )

At  $y=0$ ,  $\frac{\partial f}{\partial y} = -3 \Rightarrow y=0$  is a sink.

At  $y=-3$ ,  $\frac{\partial f}{\partial y} = -3 - 2(-3) = 3 \Rightarrow y=-3$  is a source

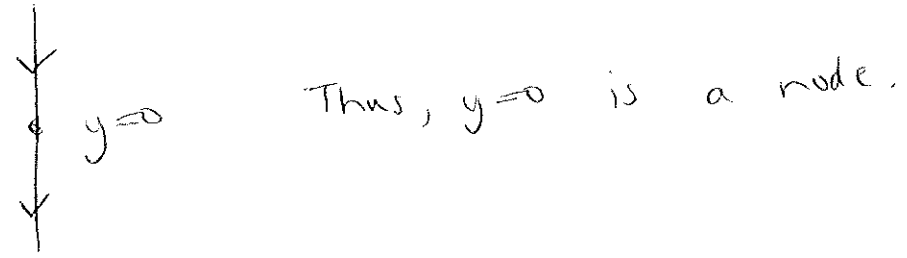


(b)  $\frac{dy}{dt} = -y^2 = f(y)$

Equilibrium is  $y=0$

$\frac{\partial f}{\partial y} = -2y = 0$  at  $y=0$

Thus linearisation does not tell us the type of the equilibrium at  $y=0$ . However,  $-y^2 \leq 0$  for all  $y$  so  $\frac{dy}{dt} \leq 0$  for all  $y \Rightarrow y$  decreases with time except at  $y=0$ . The phase line is, therefore:



$$(c) \quad \frac{dy}{dt} = 3y - y^2 = y(3-y)$$

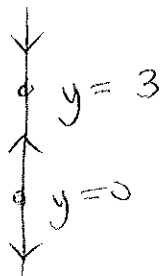
Equilibria are  $y=0$ ,  $y=3$ .

$$\frac{\partial f}{\partial y} = 3 - 2y$$

At  $y=0$ ,  $\frac{\partial f}{\partial y} = 3 \Rightarrow y=0$  is a source.

At  $y=3$ ,  $\frac{\partial f}{\partial y} = -3 \Rightarrow y=3$  is a sink.

Hence the phase line is:



$$(d) \quad \frac{dy}{dt} = ay - y^2 = y(a-y)$$

Equilibria are at  $y=0$  and  $y=a$ .

$$\frac{\partial f}{\partial y} = a - 2y$$

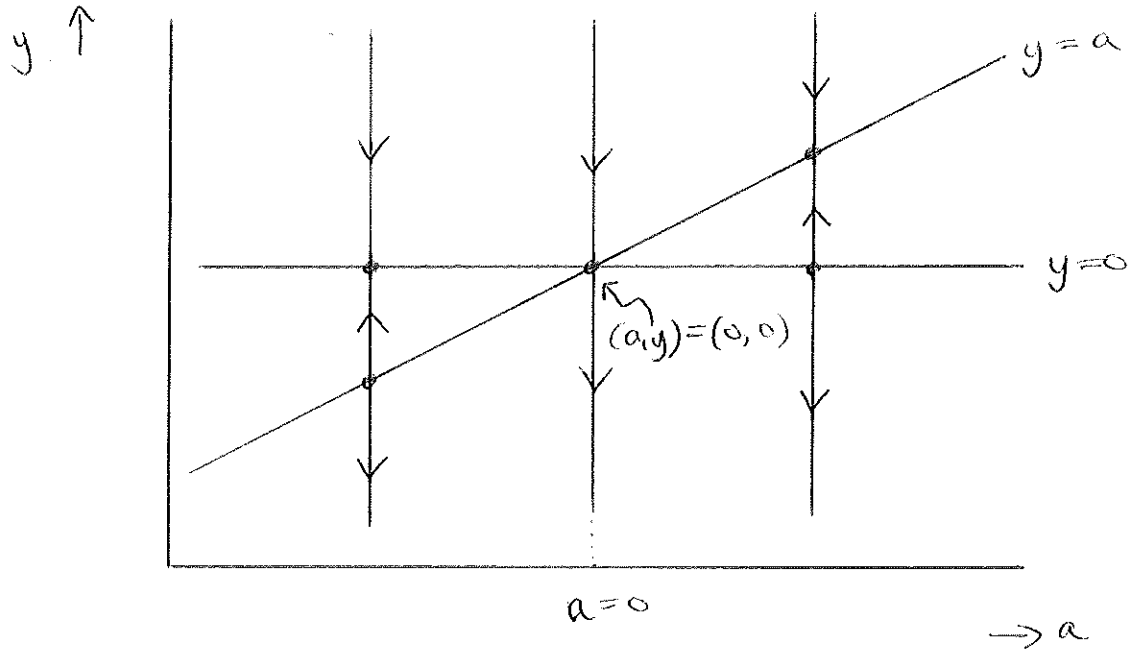
At  $y=0$ ,  $\frac{\partial f}{\partial y} = a \Rightarrow y=0$  is a sink if  $a < 0$   
 $y=0$  is a source if  $a > 0$

If  $a=0$ ,  $y=0$  is a node, from part (b).

At  $y=a$ ,  $\frac{\partial f}{\partial y} = -a \Rightarrow y=a$  is a sink if  $a > 0$   
 $y=a$  is a source if  $a < 0$

If  $a=0$ ,  $y=a$  is a node, from part (b).

Bifurcation diagram



Bifurcation is at  $a=0$ .

Q3 (a)  $A = \begin{pmatrix} -2 & 3 \\ 0 & -1 \end{pmatrix}$  has eigenvalues  $-2$  and  $-1$  with eigenvectors  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$  respectively.

The straightline solns are therefore

$$Y(t) = c_1 e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad Y(t) = c_2 e^{-t} \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

(b) General solution:

$$Y(t) = c_1 e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

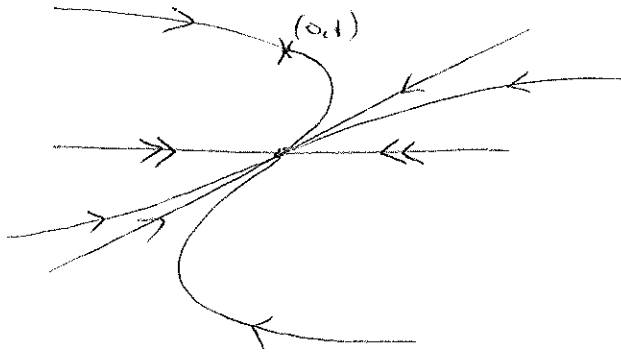
(c)  $Y(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\Rightarrow \begin{cases} c_1 + 3c_2 = 0 \\ c_2 = 1 \end{cases} \quad \text{i.e. } \begin{cases} c_1 = -3 \\ c_2 = 1 \end{cases}$$

$$\text{so } y(t) = -3e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + e^{-t} \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$\text{or } (x(t), y(t)) = (3e^{-t} - 3e^{-2t}, e^{-t})$$

(d)

(e) As  $t \rightarrow \infty$  all solutions tend to  $(0,0)$ .

$$\underline{Q4} \quad \frac{dc}{dt} = kc(100-c) - s = 100kc - kc^2 - s$$

(a) The term  $100kc$  represents growth of the population in the absence of  $s$  (i.e. when  $s=0$ ) and when  $c \ll 100$ . This means the population grows linearly when the population is small enough (and for  $s=0$ ).

The term  $-kc^2$  is a logistic term. It ensures that the population cannot grow forever. For instance, if  $s=0$ , then the population will decrease if  $c > 100$  because of this term. The term models competition between cockroaches (e.g. for food, space, etc.)

⑥

The term  $-s$  models some negative effect that is independent of the size of the population. For instance this term might model the effect of a cockroach trap that removes  $s$  (or, better,  $100s$ ) cockroaches from the restaurant per week.

(b) If  $c \ll 100$  and  $J=0$ ,  $\frac{dc}{dt} \approx 100kc$

$$\frac{dc}{dt} = 0.1c \Rightarrow 100k = 0.1$$

$$\text{or } k = 10^{-3}$$

(c) Equilibrium solns satisfy

$$100kc - kc^2 - s = 0$$

$$c = \frac{-100k \pm \sqrt{(100k)^2 - 4(-s)(-k)}}{-2k}$$

$$= 50 \pm \frac{\sqrt{(100k)^2 - 4ks}}{2k}$$

The maximum value occurs for  $J=0$ , in which case  $c=100$ . This means the maximum possible population of cockroaches is 100,000.

( $c=1 \Rightarrow 1000$  cockroaches).

Q5

$$(a) \quad f(t, y) = \frac{y^2}{t} + t$$

$$\frac{\partial f}{\partial y} = \frac{2y}{t}$$

Both  $f$  and  $\frac{\partial f}{\partial y}$  are continuous functions of  $y$ , and both are continuous functions of  $t$  except at  $t=0$ . The initial condition is  $t=2, y=0$ . Since both  $f$  and  $\frac{\partial f}{\partial y}$  are continuous at  $t=2, y=0$ , the Existence and Uniqueness Theorems guarantee that the IVP has a unique soln.

(b). Any initial condition with  $t=0$  violates the hypotheses of the Existence and Uniqueness Theorems. So, for instance,  $y(0)=1$  is an initial condition for which the IVP is not ~~guaranteed~~ guaranteed to have a unique solution.