

1. Consider the linear system

$$\frac{dY}{dt} = AY,$$

where A is as given below. For each choice of A :

- Sketch the phase portrait.
- Use `pplane` to draw the phase portrait and compare with your sketch.
- Describe the long term behaviour of the solutions.
- Write down the general solution of the system in terms of real-valued functions.

(a) $A = \begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix}$. Eigenvalues are $-3, -3$.

Eigenvector is $(1, 1)^T$.

(b) $A = \begin{pmatrix} 1 & 2 \\ -2 & -4 \end{pmatrix}$. Eigenvalues are 0 and -3 .

Eigenvectors are $(2, -1)^T$ and $(-1, 2)^T$ respectively.

2. Consider the following nonlinear system of equations:

$$\begin{aligned} \frac{dx}{dt} &= x - y \\ \frac{dy}{dt} &= x(y^2 - 1) \end{aligned}$$

Work out your answers by hand for parts (a) and (b).

- Find all equilibria and determine their types.
- For each equilibria, sketch a phase portrait showing the behaviour of solutions in the associated linearised system.
- Check your answers using `pplane`.

[Final question over page]

3. Challenge question:

Use `pplane` to investigate the following nonlinear system as the parameter α changes.

$$\begin{aligned}\frac{dx}{dt} &= \alpha x + y + \sin(x) \\ \frac{dy}{dt} &= x - y\end{aligned}$$

- (a) For what range of α is there more than one equilibrium?

Hint: The behaviour of the system is more interesting for $\alpha < 0$ than $\alpha > 0$! Try starting with the range $-4 < \alpha < 1$.

- (b) Once you have seen how the system behaves, you may find it useful to consider what happens to $\frac{dx}{dt} = 0$ and $\frac{dy}{dt} = 0$ as α is varied.

Can you describe what is happening?